Tempo[™] Automation Control Software

DYNAMIC SCHEDULING FOR LABCYTE AUTOMATION SYSTEMS



Tempo™ Automation control software

BROCHURE Version 2.1 | MAY 2017



LABCYTE INC. 170 Rose Orchard Way San Jose, CA 95134 USA

Toll-free: +1 877 742-6548 | Fax: +1 408 747-2010



© 2017 LABCYTE INC. All rights reserved.

Tempo[™] Automation Control Software

Dynamic Scheduling for Labcyte Automation Systems



Tempo Automation Control Software offers a research-friendly interface for scheduling the Access™ Laboratory Workstation protocols. In a dynamic fashion, Tempo software manages all tasks including sample management, plate handling, liquid handling, detection, and Laboratory Information Management System (LIMS) updates without custom programming or scripting. Included with all Access Workstations, Tempo software is the only platform that allows researchers to rapidly create automation routines incorporating protocols developed with Labcyte Echo® Software Applications.

Efficient Integration

Ensure maximum throughput and walk-away time



Automation Routines Optimized for Echo® Liquid Handlers

Research-friendly Interface to Automate Any Workflow



- Import any Echo Software Application protocol
- Integrate a range of laboratory devices
- No scripting or custom programming required
- O Dynamic, event-driven scheduling adjusts on the fly
- Guided error recovery to quickly resume runs

Intuitive Interface



Echo® 555 LIQUID HANDLER

Seemless Integration with Echo Software Applications

Develop complex automation protocols with little experience

Echo Software Applications utilize interactive wizards and graphics to develop complex liquid transfer protocols for Echo systems. Tempo Software imports these protocols and coordinates Echo liquid handling actions, robotic plate movements, and tasks performed by integrated devices into a fully optimized schedule — without requiring users to build loops, write custom scripts, or manage external programs.



Key Features

Plate Storage Control

Tempo software's plate storage control tracks plate properties in real-time. The status of various plate properties, such as plate type, lid type, plate location, barcode, and seal presence is available in a customizable table that is continuously updated during protocol runs. In addition to plate properties, the table also identifies plates that have been allocated to a run or rendered invalid after analysis with the Echo Plate Audit application.

Runtime Actions

After importing an Echo software protocol, Tempo software provides a list of plate handling actions that can occur before or after Echo liquid handling tasks. The actions available are dynamically generated based on the devices integrated. Barcode reading, bulk filling, shaking, sealing, centrifuge, peeling, and detection are some of the actions available.

Barcode Handling

If a Tempo software protocol is processing samples according to a pick list, barcode verification is enabled. Barcodes are tracked in the plate storage table and verified by Access or POD barcode reading stations and Echo system barcode readers throughout a protocol run. Operators are notified of missing or mismatched barcodes with step-by-step recovery guidance to continue the run.

Customizable view of plate properties tracked in real-time

Aller .	Pro	otocols F	Nates Run	s Hardw	are /	Admin	in II							_
P	New (Open S rotocol Pro	ave Print stocol Protoc) al Pr	Edit otocol	Error Check	Run Setup Wizard	Microsot Excel	Echo Array Maker	Ech	Cherry E Pick	icho Dos Respons	e- Echo e Ai	Plate udit
			Protoco	I Managem	ent				Appl	icatio	n Shortcuts			
0	Peck	🖸 💀 Ter	nporary O	Delidder										
	Full Vie	w												
-	Rack/Sta	ck 1 RAL	-20 (20-plate)	_				Rack/Sta	ck 2 RAL-20 (2	0-plat	e)			
	Barcode	Туре	Lid	Category	Status	Sealed	Location	Barcode	Туре	Lid	Category	Status	Sealed	Loc
20	001875	1536LDV	MicroClime	Source	0	No	deck://Deck/1/20/		1536LDV_Dest		Destina	Θ	Yes	deci
19	001874	1536LDV	MicroClime	Source	0	No	deck://Deck/1/19/		1536LDV_Dest		Destina_	•	Yes	dec
18	001873	1536LDV	MicroClime	Source	0	No	deck://Deck/1/18/		1536LDV_Dest		Destina	0	Yes	dec
17	001872	1536LDV	MicroClime	Source	0	No	deck://Deck/1/17/		1536LDV_Dest		Destina_	Θ	Yes	dec
16	001871	1536LDV	MicroClime	Source	0	No	deck://Deck/1/16/		1536LDV_Dest		Destina	0	Yes	dec
15	001870	1536LDV	MicroClime	Source	0	No	deck://Deck/1/15/		1536LDV_Dest		Destina	Θ	Yes	dec
14	001869	1536LDV	MicroClime	Source	Θ	No	deck://Deck/1/14/		1536LDV_Dest		Destina	•	Yes	dec
13	001868	1536LDV	MicroClime	Source	0	No	deck://Deck/1/13/		1536LDV_Dest		Destina	Θ	Yes	dec
12	001867	1536LDV	MicroClime	Source	•	No	deck://Deck/1/12/		1536LDV_Dest		Destina	•	Yes	dec
11	001866	1536LDV	MicroClime	Source	0	No	deck://Deck/1/11/		1536LDV_Dest		Destina_	Θ	Yes	dec
10	001865	1536LDV	MicroClime	Source	•	No	deck://Deck/1/10/		1536LDV_Dest		Destina	Θ	Yes	dec
9	001864	1536LDV	MicroClime	Source	0	No	deck://Deck/1/9/		1536LDV_Dest		Destina	Θ	Yes	dec
8	001863	1536LDV	MicroClime	Source	0	No	deck://Deck/1/8/		1536LDV_Dest		Destina	Θ	Yes	dec
7	001862	1536LDV	MicroClime	Source	•	No	deck://Deck/1/7/		1536LDV_Dest		Destina	Θ	Yes	dec
6	001861	1536LDV	MicroClime	Source	0	No	deck://Deck/1/6/		1536LDV_Dest		Destina	Θ	Yes	dec
5	001860	1536LDV	MicroClime	Source	•	No	deck://Deck/1/5/		1536LDV_Dest		Destina	0	Yes	deci
4	001859	1536LDV	MicroClime	Source	0	No	deck://Deck/1/4/		1536LDV_Dest		Destina	0	Yes	dec
3	001858	1536LDV	MicroClime	Source	•	No	deck://Deck/1/3/		1536LDV_Dest		Destina	0	Yes	dec
2	001857	1536LDV	MicroClime	Source	0	No	deck://Deck/1/2/		1536LDV_Dest		Destina	Θ	Yes	deci
1	001856	1536LDV	MicroClime	Source	0	No	deck://Deck/1/1/		1536LDV_Dest		Destina_	0	Yes	dec



un	0														Тетро	Software		
0	leck Delidde Plate Nanc Plate Nanc	r Temporary P Temporary P Read all plates	In and were address addre Address address a Address address addre Address address a Address address ad	impty Plat sostion Seele	e Add Plates	Racko Ste Type Racko Ste	ndk Go T Rac	o Invento	ry C Ban	2 lear codes								
F	Full View																	
	Rack/Stack 1	RAL-20 (20-plate	e)					Rack/Sta	ck 2 F	R4L-20	(20-pl	ate)			Rack/Sta	ok 3 RAL-	20 (20-plate)	
	Barcode	Name	Туре	Lid	Category	Status	Sealed	Barcode	Name	Type	Ud .	Category	Status	Sealed	Barcode	Name	Type	L
20	-					0							0					
19						0							0					
18						0							0					
17						0							0					
16						0							0					
15						0							0					
14						0							0					
13	11316	Source[1]	384PP	MicroClime	Source	0	No						0					
12	11318	Source[1]	6RES	MicroClime	Source	0	No						0					
11	-					0							0					
10	11308	Destination[10]	Corning 3724 black 1536	MicroClime	Destination	0	Yes						0					
9	11307	Destination[9]	Corning 3724 black 1536	MicroClime	Destination	0	Yes						0					
8	11306	Destination[8]	Corning 3724 black 1536	MicroClime	Destination	0	Yes						0					
	11305	Destination[7]	Corning 3724 black 1536	MicroClime	Destination	0	Yes						0					
6	11304	Destination[6]	Corning 3724 black 1536	MicroClime	Destination	9	Yes						0					
5	11303	Destination[5]	Corning 3724 black 1536	MicroClime	Destination	0	Yes						0					
4	11302	Destination[4]	Corning 3724 black 1536	MicroClime	Destination	0	Yes						0		Doug001	Plate-001	384PP_Dest	
3	11301	Destination[3]	Corning 3724 black 1536	MicroClime	Destination	0	Yes						0					
2	11332	Destination[2]	Corning 3724 black 1536	MicroClime	Destination	0	Yes						0					
1	11331	Destination[1]	Corning 3724 black 1536	MicroClime	Destination	0	Yes						0					



continued...

Device Management

To simplify the management of integrated devices, Tempo software provides easy access to device parameters and options. Options to perform device maintenance, reset cycle counts, and set devices on or offline are just a few examples. Integrated devices can be operated in a standalone or manual fashion when they are not required for a protocol in progress.

Quickly initiate device-specific tasks and view essential parameters



Simultaneous Protocols

Tempo software allows for the running of multiple protocols in parallel. The software automatically manages plate and device handling based on priorities designated for each protocol by the user. Users can start multiple Tempo protocols simultaneously; whether they involve an Echo protocol or not.

Quickly assign priorities to each protocol running simultaneously



Scheduling of device utilization between simultaneous protocols

	Zoo	m factor:	0											
Device Plate	Merge	d: Schedule	er_878.xml	Schedule	r_879.xr	nl								
			<i>q</i>		÷		<i>i</i>				2014-08-25			
		5:40PM	5:	44PM		5:48PM		5:53PM		5:57P	M	6:02PM		6:06PM
	0:14				17:5	0:12				18:0	0:13			18
Centrifuge	81													
Echo1230														
Echo1408											1		1	
Peeler								۵				۵		
PLC	Ú.													
Robot	8													
Sealer	1			0	0	0			0		8	1	8	8
Temporary	1													

Key Features continued...

Guided Error Recovery

In the event of an error, Tempo software provides operators with interactive prompts to return the system to an operating state. Error recovery options include manual plate removal, manual device command and standard error handling options such as abort, ignore, and retry.

	Robot error moving to slot: Failed to move to new location								
Time:	2012-12-17 13:11:02								
Job:	Move Plate (ID:642 Owner:610) [deck://Deck/2/4/-> vspin://Centrifuge/1/]								
Plate:	Plate-004 [ID:23474]								
Device:	Device: Robot								
Reserved Wark	; ob as complete and continue								
Mark 😰	ark job as error and continue								
😳 Mark	job as error and stop								
	job as error and abort								
🔛 Mark									

🔔 Deck Door Opener	đ				х			
Ma	in Door is op	en - Sy	/stem	Disabled	ł			
Instructions	Safety Hardware	Doors	Robot					
1.Open enclosure doors, if applicable.								
a.Manually remove or replace labware as necessary.								
2.Close the enclose	2.Close the enclosure doors.							
3.Click on the Add	3.Click on the Add to Error List for all error windows on the screen.							
4.Disengage E-Sto	4.Disengage E-Stop button.							
5.Click on Reset S and the door sens	5.Click on Reset Safety Relay in the Safety Hardware tab to reset the E-Stop circuity and the door sensors, and allow normal operation to resume.							
6.Use Robot tab in	6.Use Robot tab in this window to jog robot to a safe location.							
a.Click on the	a.Click on the Origin button to re-origin the robot.							
7.Click on the Initi	7.Click on the Initialization button to re-initialize system devices.							
8.Click on the Cor	8.Click on the Control Panel button and select the Plates tab.							
a.Click the M	a.Click the Manually Removed button for plates that have been removed.							
b.Click to Edi	b.Click to Edit button to change the current location of any plate							
c.Click the Ar	c.Click the Archive All button to return plates to their original location.							
d.Click the Re	d.Click the Resume button to resume the scheduler							
9. Close the Control	9. Close the Control Panel and the E-Stop status form.							
Initialization	Control Panel	Pov	wer On De	rices	Close			

Error Handling Options

Runtime error prompts offer ways to quickly recover and continue

Error Recovery Wizards

Step-by-step guidance to recover quickly from any error or emergency stop



Notification and Reports

Runtime notifications can be configured globally or for each individual protocol. Notifications are reported in the run status view and can be communicated through email. All activities that occur during a run are recorded into a set of reports organized by plate activities, device actions, errors, run details and more.

Tempo software offers a growing list of advanced features

External Program Integration

Initiate external programs before or after protocols begin to validate protocols against custom rules, update LIMS databases, or interact with external software applications

Device Pooling

Split plate handling activity across common devices to increase throughput

External Data Management

All data from integrated devices (including detection platforms) can be routed to user-defined directories for easy access at run completion

Gantt Chart Viewer

Compare the timing of events across multiple protocols to analyze the impacts of priorities and other scheduling considerations

Counter-balance Management

Counter-balance plates can be mapped to plates used across Tempo software protocols. As soon as a protocol plate is ready to start a centrifuge step, Tempo software automatically schedules the loading of the appropriate counterbalance plate





LABCYTE INC.

170 Rose Orchard Way San Jose, CA 95134 USA

Toll-free: +1 877 742-6548 | **Fax:** +1 408 747-2010

All product names and brands are properties of their respective owners.

© 2017 LABCYTE INC. All rights reserved. Labcyte®, Echo®, MicroClime®, the Labcyte logo, and Access™ are registered trademarks or trademarks of Labcyte Inc., in the U.S. and/or other countries.

+1 408 747-2000
+353 1 6791464
+81 03 5530 8964
+61 39018 5780
+1 408 747-2000

info-us@labcyte.com info-europe@labcyte.com info-japan@labcyte.com info-asia@labcyte.com info-us@labcyte.com

FOR RESEARCH USE ONLY. Not for use in diagnostic procedures.

BRH-TASW-2.1 MAY 2017